

Divide-and-Conquer Sequential Matrix Diagonalisation for ParaHermitian Matrices

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Background

Motivation: Several algorithms for the calculation of a polynomial matrix eigenvalue decomposition (PEVD) have been developed. The PEVD can be used in a number of broadband multichannel problems, including MIMO, beamforming, and angle of arrival estimation.

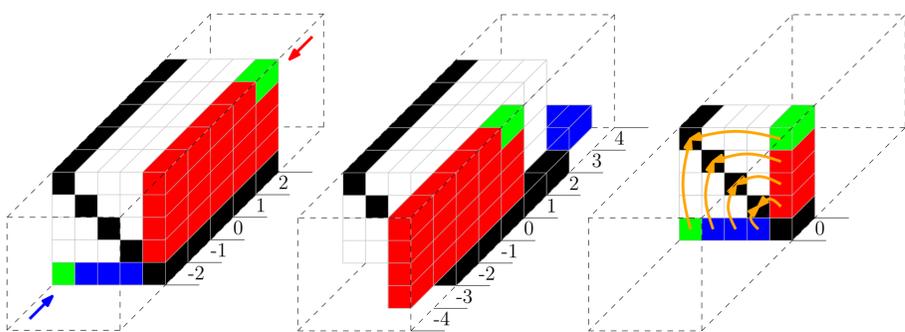
Aim: Develop a low complexity algorithm for the PEVD by employing divide-and-conquer strategies alongside existing sequential matrix diagonalisation (SMD) [1] algorithm.

- ▶ A space-time covariance matrix $\mathbf{R}[\tau] = \mathcal{E}\{\mathbf{x}[n]\mathbf{x}^H[n-\tau]\}$, $\mathbf{R}[\tau] \in \mathbb{C}^{M \times M}$, can be constructed from the auto- & cross- correlation sequences of vector $\mathbf{x}[n] \in \mathbb{C}^M$, where $\mathbf{x}[n]$ is obtained from, e.g., an M -element sensor array.
- ▶ $\mathbf{R}[\tau]$ exhibits symmetry about its centre: $\mathbf{R}[\tau] = \mathbf{R}^H[-\tau]$.
- ▶ Cross spectral density matrix $\mathbf{R}(z) = \sum_{\tau} \mathbf{R}[\tau]z^{-\tau}$ is a polynomial matrix and exhibits paraHermitian symmetry: $\tilde{\mathbf{R}}(z) = \mathbf{R}^H(1/z^*) = \mathbf{R}(z)$.
- ▶ The PEVD has been defined as an extension of the eigenvalue decomposition (EVD) to paraHermitian polynomial matrices in [2]. The PEVD uses finite impulse response (FIR) paraunitary matrices [3] to approximately diagonalise and spectrally majorise [4] a space-time covariance matrix:

$$\mathbf{R}(z) \approx \tilde{\mathbf{F}}(z)\mathbf{D}(z)\mathbf{F}(z)$$

Existing Iterative PEVD Algorithms

- ▶ Existing iterative PEVD algorithms consist of three major steps:
 1. Determine the elements to be shifted onto the zero-lag;
 2. Shift the appropriate row and column onto the zero-lag;
 3. Transfer energy from the zero-lag onto the diagonal.



$$1. \{k^{(i)}, \tau^{(i)}\} = \arg \max_{k, \tau} \|\tilde{s}_k^{(i-1)}[\tau]\|_{\infty} \quad 2. \mathbf{S}^{(i)}(z) = \Lambda^{(i)}(z)\mathbf{S}^{(i-1)}(z)\tilde{\Lambda}^{(i)}(z) \quad 3. \mathbf{S}^{(i)}(z) = \mathbf{Q}^{(i)}\mathbf{S}^{(i)}(z)\mathbf{Q}^{(i)H}$$

- ▶ Second order Sequential Best Rotation (SBR2) [2] algorithm uses a Jacobi transformation applied to all lags for step 3.
- ▶ The Sequential Matrix Diagonalisation (SMD) [1] algorithm uses a full EVD of the zero-lag (applied to all lags) for step 3.
- ▶ Product over I iterations is the paraunitary matrix $\mathbf{F}(z) = \prod_{i=1}^I \mathbf{Q}^{(i)}\Lambda^{(i)}(z)$.

Divide-and-Conquer Sequential Matrix Diagonalisation

- ▶ Research in [5]–[7] has demonstrated that complexity reduction can be obtained by using a divide-and-conquer approach to eigenproblems.
- ▶ Inspired by this work, here we describe a divide-and-conquer approach for the PEVD, which can be utilised to reduce algorithm complexity.
- ▶ The framework of the developed algorithm — titled divide-and-conquer sequential matrix diagonalisation (DC-SMD) — is based on the SMD algorithm.

- ▶ While the SMD algorithm attempts to diagonalise an entire $M \times M$ paraHermitian matrix at once, the DC-SMD algorithm first divides the matrix into a number of smaller, independent paraHermitian matrices, before diagonalising — or conquering — each matrix separately.

- ▶ An algorithm named sequential matrix segmentation (SMS) is used to recursively divide $\mathbf{R}(z)$ into multiple independent paraHermitian matrices. Each of these is stored on the diagonal of matrix $\mathbf{R}'(z)$; thus, $\mathbf{R}'(z)$ is block diagonal by construction.

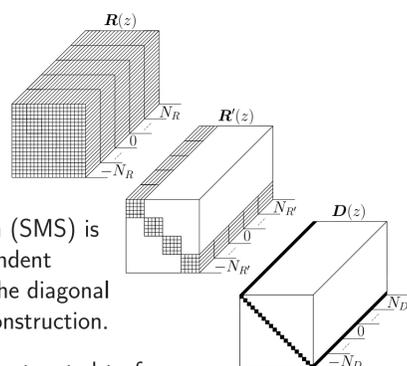
- ▶ The paraunitary matrices generated by SMS are concatenated to form an overall dividing matrix $\tilde{\mathbf{G}}(z)$ such that $\mathbf{R}(z) \approx \tilde{\mathbf{G}}(z)\mathbf{R}'(z)\mathbf{G}(z)$.

- ▶ Each block on the diagonal of matrix $\mathbf{R}'(z)$ is then diagonalised in sequence through the use of the SMD algorithm.

- ▶ The diagonalised outputs, $\hat{\mathbf{D}}(z)$, are placed on the diagonal of matrix $\mathbf{D}(z)$, and the corresponding paraunitary matrices, $\hat{\mathbf{H}}(z)$, are stored on the diagonal of matrix $\mathbf{H}(z)$.

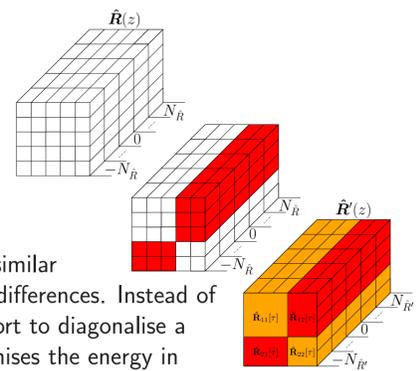
- ▶ $\mathbf{R}'(z) \approx \tilde{\mathbf{H}}(z)\mathbf{D}(z)\mathbf{H}(z)$.

- ▶ By extension, $\mathbf{R}(z) \approx \tilde{\mathbf{G}}(z)\tilde{\mathbf{H}}(z)\mathbf{D}(z)\mathbf{H}(z)\mathbf{G}(z) = \tilde{\mathbf{F}}(z)\mathbf{D}(z)\mathbf{F}(z)$.



Recursive Polynomial Matrix Segmentation

- ▶ Sequential matrix segmentation (SMS) is a novel variant of SMD designed to segment an input matrix $\hat{\mathbf{R}}(z) \in \mathbb{C}^{M' \times M'}$ into two independent paraHermitian matrices $\hat{\mathbf{R}}_{11}(z) \in \mathbb{C}^{(M'-P) \times (M'-P)}$ and $\hat{\mathbf{R}}_{22}(z) \in \mathbb{C}^{P \times P}$, and two matrices $\hat{\mathbf{R}}_{12}(z) \in \mathbb{C}^{(M'-P) \times P}$ and $\hat{\mathbf{R}}_{21}(z) \in \mathbb{C}^{P \times (M'-P)}$, where $\hat{\mathbf{R}}_{12}(z) = \hat{\mathbf{R}}_{21}(z)$ are approximately zero.

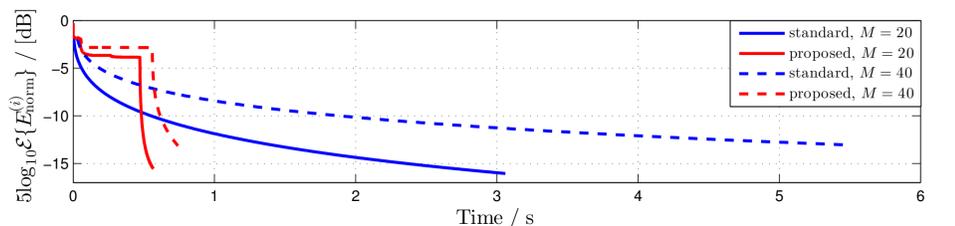
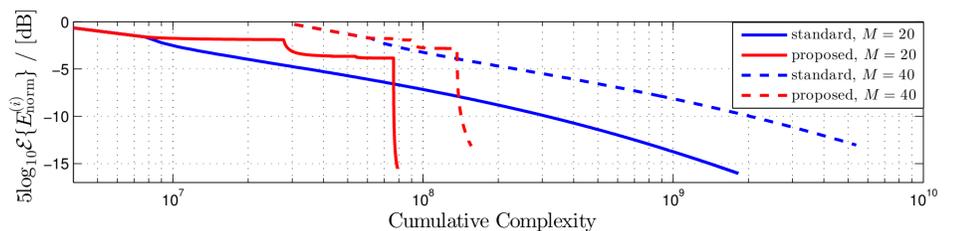


- ▶ The SMS algorithm is initialised and operates in a similar manner to the SMD algorithm, but with a few key differences. Instead of iteratively shifting single row-column pairs in an effort to diagonalise a paraHermitian matrix $\mathbf{S}^{(i)}(z)$, SMS iteratively minimises the energy in select regions of $\mathbf{S}^{(i)}(z)$ in an attempt to segment the matrix.

Independent Conquering of Divided Polynomial Matrices

- ▶ At this stage of DC-SMD, $\mathbf{R}(z) \in \mathbb{C}^{M \times M}$ has been segmented into multiple independent paraHermitian matrices, which are stored as blocks on the diagonal of $\mathbf{R}'(z)$.
- ▶ Each matrix can now be diagonalised individually through the use of the SMD algorithm.
- ▶ Upon completion, the SMD algorithm returns matrices $\hat{\mathbf{H}}(z)$ and $\hat{\mathbf{D}}(z)$, which contain the polynomial eigenvectors and eigenvalues for input matrix $\mathbf{A}(z)$, respectively.
- ▶ At iteration γ of this stage, $\mathbf{A}(z)$ contains the γ th block of $\mathbf{R}'(z)$ from the bottom-right.

Results



Method	MSE		Paraunitary filter length	
	$M = 20$	$M = 40$	$M = 20$	$M = 40$
standard (SMD)	1.991×10^{-6}	5.643×10^{-7}	116.8	79.13
proposed (DC-SMD)	7.991×10^{-6}	3.477×10^{-6}	154.3	121.8

Conclusions

- ▶ We have proposed an alternative technique to compute the polynomial EVD of a paraHermitian matrix; this algorithm — named DC-SMD — makes use of a divide-and-conquer approach to the PEVD.
- ▶ DC-SMD operates with lower computational complexity and execution time than the traditional SMD algorithm.
- ▶ These benefits come with the disadvantage of increasing the mean squared reconstruction error and the paraunitary filter length.
- ▶ A further advantage of the DC-SMD algorithm is its ability to produce multiple independent paraHermitian matrices, which may be processed in parallel.
- ▶ Simulation results demonstrate that DC-SMD outperforms SMD more significantly for larger values of M ; therefore, DC-SMD is suitable for broadband multichannel applications with a large number of sensors.

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