

Robust Unmixing Algorithms for Hyperspectral Imagery



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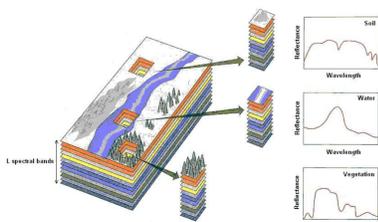
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1. Introduction

Hyperspectral imagery

- same scene observed at different wavelengths
- pixel represented by a vector of hundreds of measurements



Hyperspectral imaging concept.

⇒ Analysis of robust algorithms in presence of different effects (nonlinearity NL, endmember variability EV, outliers, ...)

2. Models and algorithms

General formulation

- Residual component analysis model (RCA)

$$\mathbf{y}_n = f[\mathbf{M}\mathbf{a}_n + \phi_n],$$

- $\mathbf{M} = [\mathbf{m}_1, \dots, \mathbf{m}_R]$: matrix of endmembers
- $\mathbf{a}_n = [a_{1,n}, \dots, a_{R,n}]^T$: abundance vector
- ϕ_n : residual component
- $f(\cdot)$: function introducing noise (additive, Gaussian, Poisson, ...)

Robust nonnegative matrix factorization (RNMF) [1]

- **Observation model:** $\mathbf{y}_n^{\text{RNMF}} = \sum_{r=1}^R a_{r,n} \mathbf{m}_r + \mathbf{r}_n$
- **Assumptions:**
 - $\mathbf{r}_n, \forall n$ denote **positive residuals** that are spatially sparse
 - Two similarity measures $D(\mathbf{Y}|\mathbf{M}\mathbf{A} + \mathbf{R})$:
 - squared Euclidean distance (SED) ⇒ Gaussian noise
 - Kullback-Leibler divergence (KLD) ⇒ Poisson statistics

- **Estimation algorithm for (\mathbf{A}, \mathbf{R})**

– An optimization approach using the cost function:

$$\min_{\mathbf{A}, \mathbf{R}} \{D(\mathbf{Y}|\mathbf{M}\mathbf{A} + \mathbf{R}) + \lambda \|\mathbf{R}\|_{2,1}\}$$

where $\|\mathbf{R}\|_{2,1} = \sum_{n=1}^N \sqrt{\mathbf{r}_n^T \mathbf{r}_n}$

– Coordinate descent algorithm (CDA).

Robust Bayesian linear unmixing (RBLU) [2]

- **Observation model:** $\mathbf{y}_n = \mathbf{M}\mathbf{a}_n + \phi_n + \mathbf{e}_n$, with $\mathbf{e}_n \sim \mathcal{N}(\mathbf{0}, \Sigma)$ and a diagonal covariance $\Sigma = \text{diag}\{\sigma^2\}$
- **Assumptions:**
 - $\phi_n = \mathbf{z}_n \odot \mathbf{x}_n, \forall n$: where \odot is a term-wise product
 - The support \mathbf{z}_n is spatially-spectrally sparse and correlated
 - The values $\mathbf{x}_n, \forall n$ are independent
- **Estimation algorithm for $\Theta_1 = (\mathbf{A}, \Sigma, \mathbf{X}, \mathbf{Z}, s^2, \beta)$** where (s^2, β) are hyperparameters

– A Bayesian approach using the likelihood $f(\mathbf{Y}|\Theta_1)$ and the parameter prior distributions $f(\Theta_1)$ to build the posterior

– Posterior distribution:

$$f(\Theta_1|\mathbf{Y}) \propto f(\mathbf{Y}|\Theta_1)f(\Theta_1),$$

– Evaluate the MMSE or MAP estimators using a Markov chain Monte-Carlo (MCMC) algorithm.

RCA with mismodelling effects (RCA-ME) [3]

- **Observation model:** $\mathbf{y}_n = \mathbf{M}\mathbf{a}_n + \mathbf{d}_n + \mathbf{e}_n$, with $\mathbf{e}_n \sim \mathcal{N}(\mathbf{0}, \Sigma)$ and a diagonal covariance $\Sigma = \text{diag}\{\sigma^2\}$
- **Assumptions:**
 - $\mathbf{d}_n, \forall n$ are spectrally smooth
 - The energies of $\mathbf{d}_n, \forall n$ are spatially correlated
- **Estimation algorithm for $\Theta_2 = (\mathbf{A}, \Sigma, \mathbf{D}, \epsilon, \mathbf{w})$** where (ϵ, \mathbf{w}) are hyperparameters

– A Bayesian approach using the likelihood $f(\mathbf{Y}|\Theta_2)$ and the prior distributions $f(\Theta_2)$ to build the posterior distribution:

$$f(\Theta_2|\mathbf{Y}) \propto f(\mathbf{Y}|\Theta_2)f(\Theta_2),$$

– An optimization approach using the cost function:

$$\min_{\Theta_2} \{-\log[f(\Theta_2|\mathbf{Y})]\}$$

– CDA to approximate the MAP estimator of Θ_2 .

Characteristics of the robust models.

	Residuals			Statistics
	Positivity	Spatial	Spectral	
RNMF	✓	Sparse energies	None	-SED -KLD
RBLU	✗	Correlated and sparse support	Correlated support	$\mathcal{N}(\mathbf{0}, \Sigma)$
ME	✗	Correlated energies	Correlated values	$\mathcal{N}(\mathbf{0}, \Sigma)$

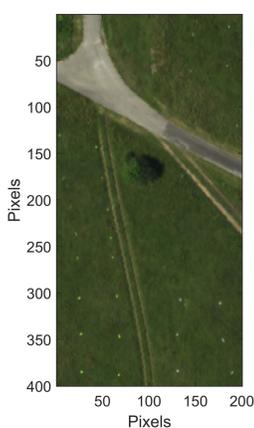
3. Results on a real image

Data description and evaluation criteria

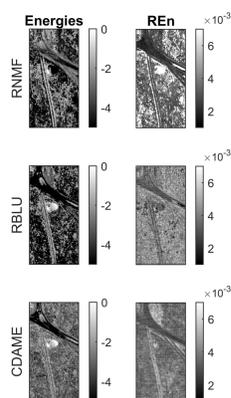
- A real image acquired by the Defence Science and Technology Laboratory (DSTL) in 2014 over Porton Down, U.K
- It contains 400×200 pixels, $L = 140$ bands in $[415, 990]$ nm, $R = 5$ components with other man-made outliers.

$$\text{RE} = \sqrt{\frac{1}{NL} \sum_{n=1}^N \|\hat{\mathbf{y}}_n - \mathbf{y}_n\|^2}$$

$$\text{SAM} = \frac{1}{N} \sum_{n=1}^N \arccos \left(\frac{\hat{\mathbf{y}}_n^T \mathbf{y}_n}{\|\hat{\mathbf{y}}_n\| \|\mathbf{y}_n\|} \right)$$

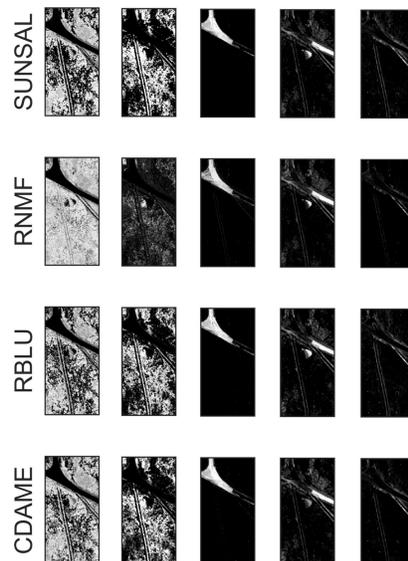


Real Porton Down image.



(Left) square root of the energies of the residuals obtained with $\|\hat{\phi}_n\|$. (Right) reconstruction error obtained with $\text{RE}_n = \frac{1}{\sqrt{L}} \|\hat{\mathbf{y}}_n - \mathbf{y}_n\|$.

Abundance maps

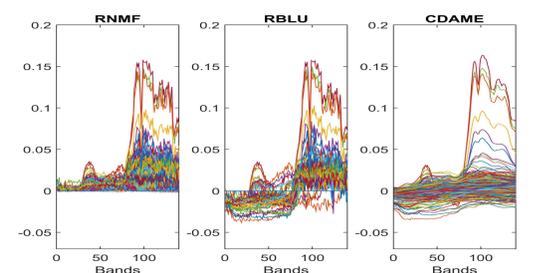


Estimated abundance maps with different algorithms (the gray scale ranges between 0 and 1). From left to right: grass, tree, soil 1, road, and soil 2.

Quantitative results

	RE ($\times 10^{-3}$)	SAM ($\times 10^{-2}$)	Time (min)
SUNSAL [4]	9.32	3.34	0.03
RNMF	7.17	2.05	23.92
RBLU	4.28	2.32	1440
CDA-ME	3.87	2.21	6.98

Unmixing performance on a real images (400×200 pixels).



Example of outlier spectra.

4. Discussion

- The robust algorithms detect man-made outliers
- Complementary results in terms of the detected physical effects, computational time and estimation quality

	Effects	Time	RE	Noise	Endmember estimation
SUNSAL [4]	LMM	+++	-	-	-
RNMF	LMM + NL	+	+	++	+
RBLU	LMM + NL EV + Shadow	-	++	++	+
CDAME	LMM + NL EV + Shadow	++	+++	++	-

Evaluation of the algorithms. (+++) best results, (-) fair results.

References

- [1] C. Févotte and N. Dobigeon, "Nonlinear hyperspectral unmixing with robust nonnegative matrix factorization," *IEEE Trans. Image Process.*, vol. 24, no. 12, pp. 4810–4819, June 2015.
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