

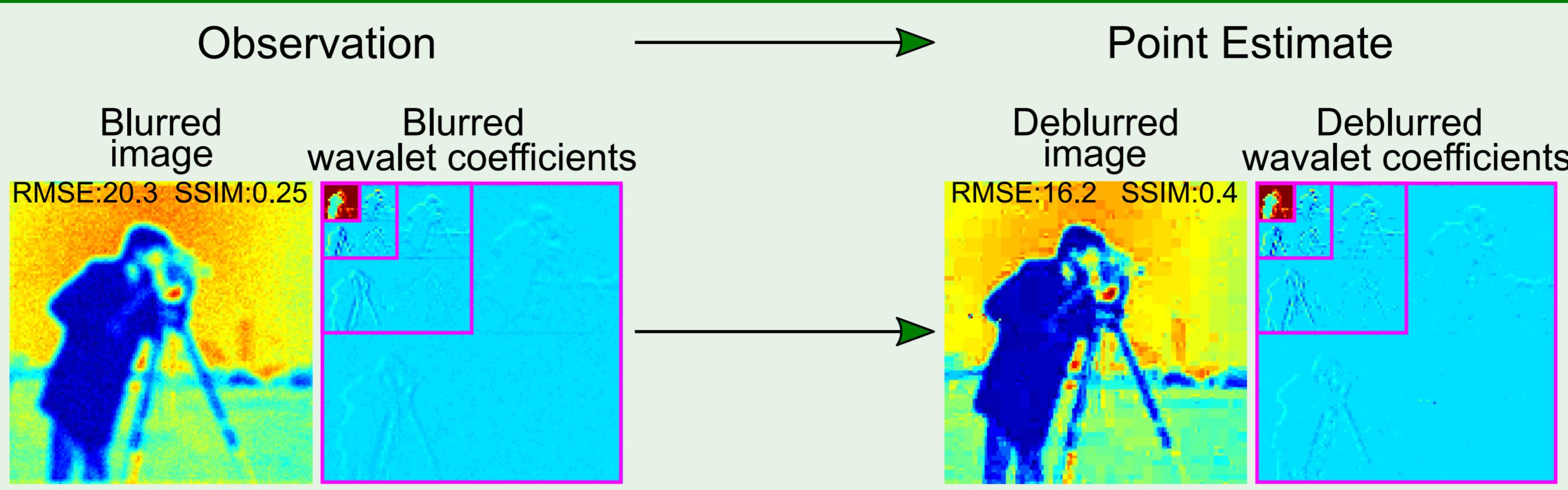
Unsupervised Expectation Propagation Method for Large-Scale Sparse Linear Inverse Problems



Dan Yao (dy2008@hw.ac.uk), Stephen McLaughlin, Yoann Altmann

School of Engineering and Physical Sciences, Heriot-Watt University, Edinburgh, UK

Problem: Uncertainty Quantification in Solving Large Scale Sparse Linear Inverse Problems



Uncertainty Quantification !

Goal

large scale observation → point estimate + uncertainty quantification

Challenges

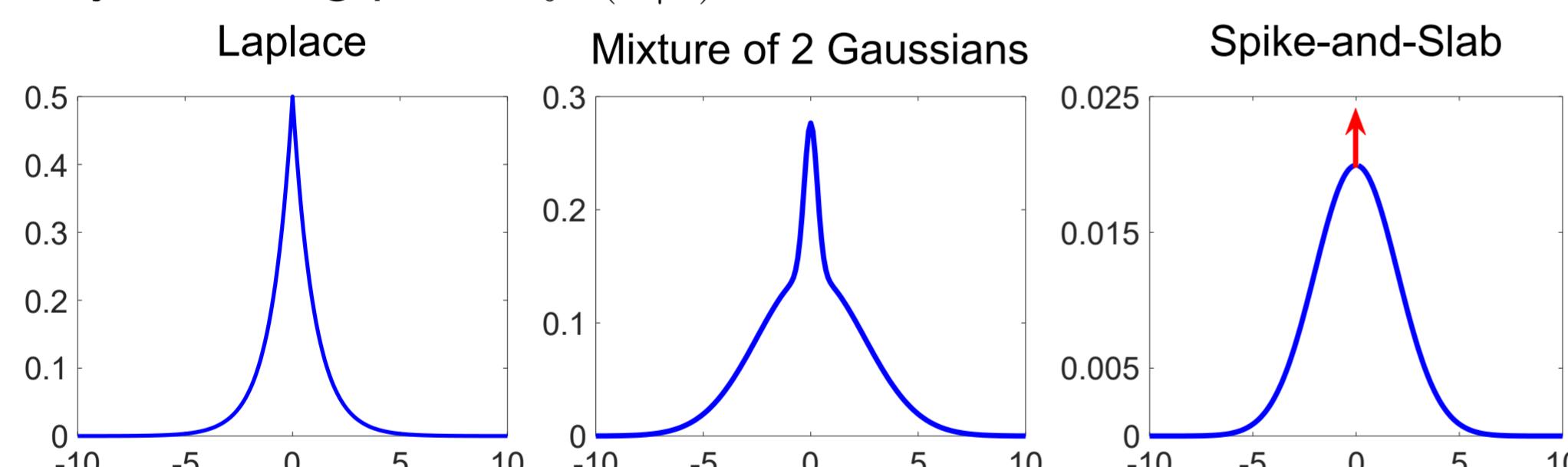
- **efficient computation** in solving large scale linear inverse problems (e.g. imaging problems)
- **optimal sparse solution** to large scale sparse linear inverse problems (e.g. in wavelet domain)
- **uncertainty quantification** for the point estimate
- **unsupervised hyperparameter estimation** when using Bayesian methods with sparsity enforcing priors

Proposed Solution: Expectation Propagation (EP) for Unsupervised Approximate Bayesian Inference

Bayesian model

likelihood: $f_{y|x}(\mathbf{y}|\mathbf{H}\mathbf{x})$

sparsity-enforcing priors: $f_x(\mathbf{x}|\boldsymbol{\theta})$



- posterior:

$$p(\mathbf{x}|\mathbf{y}, \boldsymbol{\theta}) = \frac{f_{y|x}(\mathbf{y}|\mathbf{H}\mathbf{x})f_x(\mathbf{x}|\boldsymbol{\theta})}{\int f_{y|x}(\mathbf{y}|\mathbf{H}\mathbf{x})f_x(\mathbf{x}|\boldsymbol{\theta})d\mathbf{x}}$$

- MMSE (point estimate): $\mathbb{E}_p[\mathbf{x}] = \int \mathbf{x} p(\mathbf{x}|\mathbf{y}, \boldsymbol{\theta}) d\mathbf{x}$

- covariance (uncertainty):

$$\text{Cov}_p(\mathbf{x}) = \int (\mathbf{x} - \mathbb{E}[\mathbf{x}])(\mathbf{x} - \mathbb{E}[\mathbf{x}])^T p(\mathbf{x}|\mathbf{y}, \boldsymbol{\theta}) d\mathbf{x}$$

EP for approximate Bayesian inference

$$q(\mathbf{x}|\boldsymbol{\theta}) \underset{\text{Kullback-Leibler divergence minimization}}{\approx} p(\mathbf{x}|\mathbf{y}, \boldsymbol{\theta})$$

- approximate posterior: $q(\mathbf{x}|\boldsymbol{\theta}) \approx p(\mathbf{x}|\mathbf{y}, \boldsymbol{\theta})$

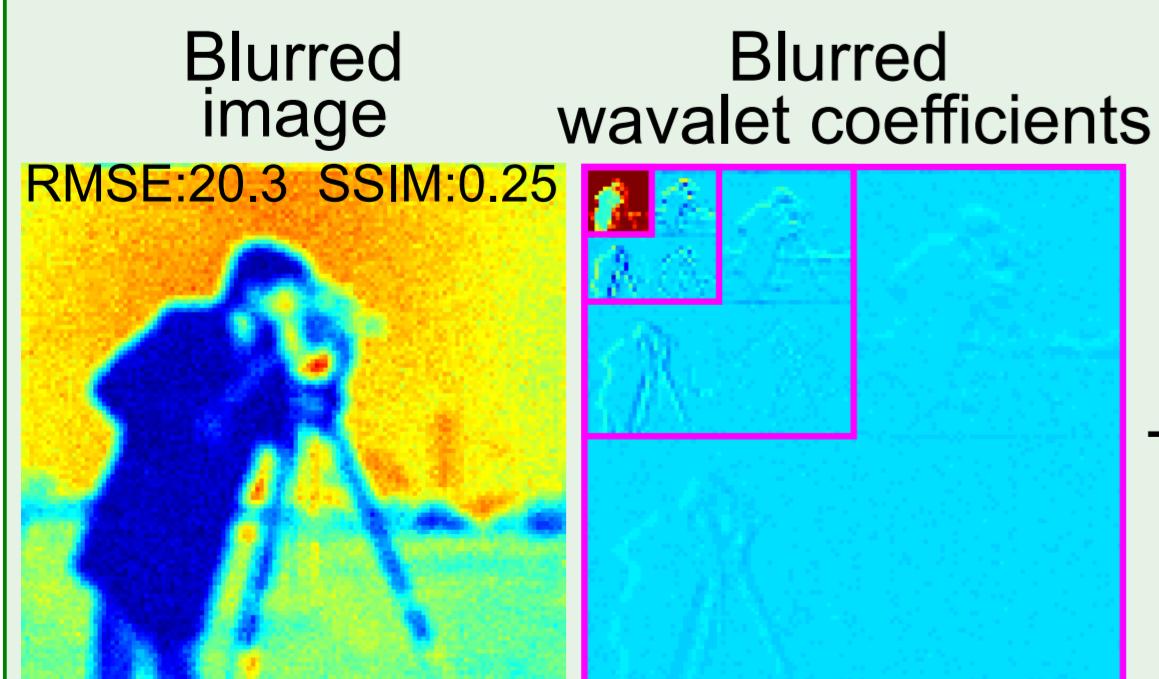
- approximate MMSE: $\mathbb{E}_q[\mathbf{x}] \approx \mathbb{E}_p[\mathbf{x}]$

- approximate covariance: $\text{Cov}_q(\mathbf{x}) \approx \text{Cov}_p(\mathbf{x})$

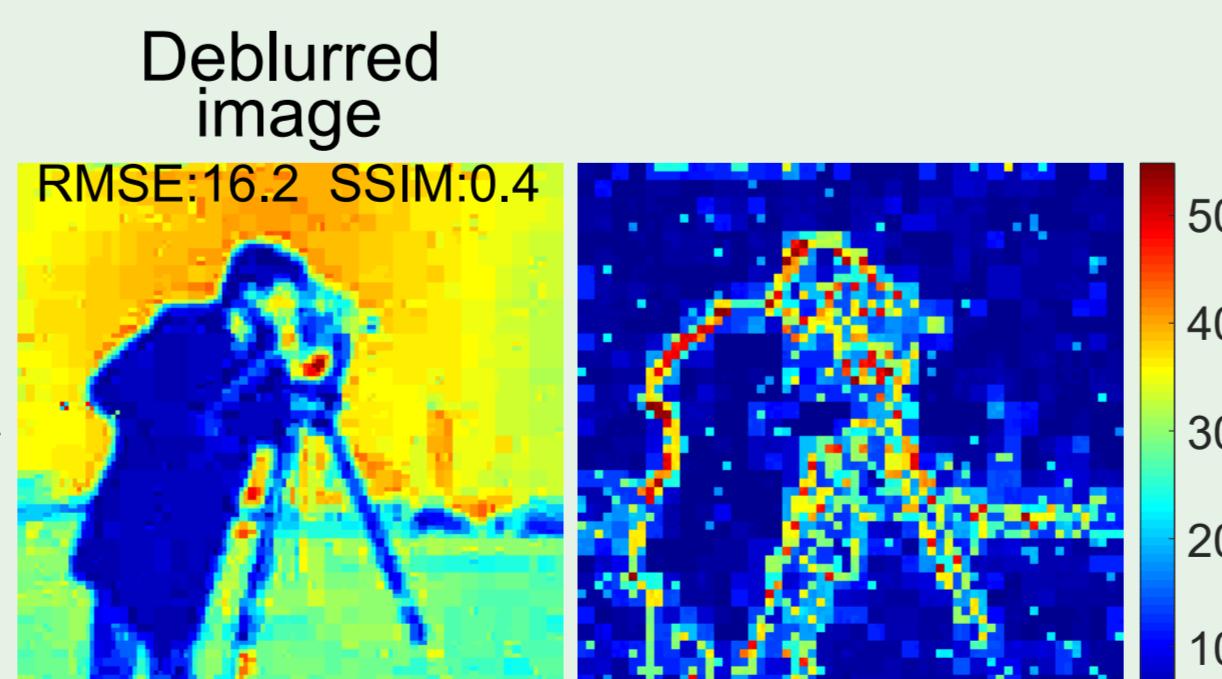
- unsupervised hyperparameter estimation:

$$\hat{\boldsymbol{\theta}} = \underset{\boldsymbol{\theta}}{\operatorname{argmax}} \mathbb{E}_{q(\mathbf{x}|\boldsymbol{\theta}^{(t-1)})} [\log f(\mathbf{y}|\boldsymbol{\theta})]$$

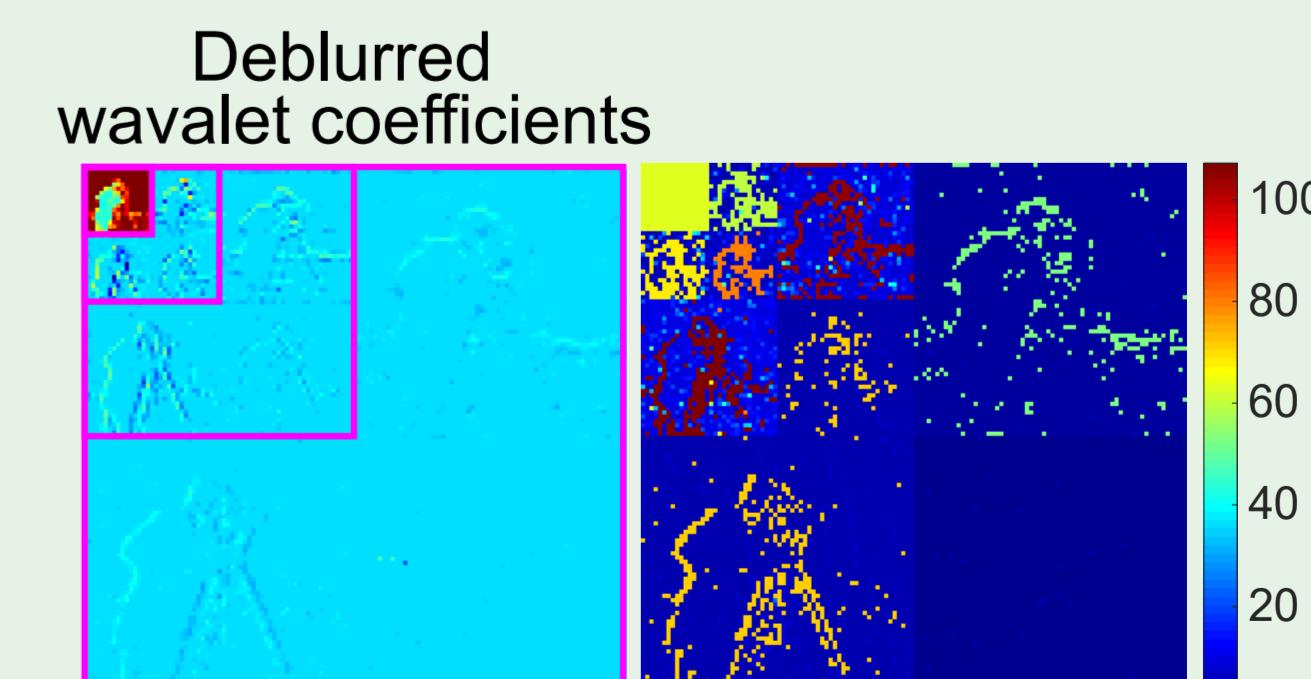
Observation



Point Estimate + Uncertainty



Point Estimate + Uncertainty



References

- [1] Dan Yao, Stephen McLaughlin, and Yoann Altmann. "Fast Scalable Image Restoration using Total Variation Priors and Expectation Propagation," IEEE Transactions on Image Processing, 2022, doi: 10.1109/TIP.2022.3202092.
[2] José Miguel Hernández-Lobato, Daniel Hernández-Lobato, and Alberto Suárez. "Expectation propagation in linear regression models with spike-and-slab priors," Machine Learning 99.3 (2015), pp. 437–487.
[3] Thomas P Minka. "Expectation propagation for approximate Bayesian inference," Proceedings of the Seventeenth conference on Uncertainty in artificial intelligence. 2001, pp. 362–369.